# Polytypic Functions Over Nested Datatypes ${ }^{\dagger}$ 

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#### Abstract

The theory and practice of polytypic programming is intimately connected with the initial algebra semantics of datatypes. This is both a blessing and a curse. It is a blessing because the underlying theory is beautiful and well developed. It is a curse because the initial algebra semantics is restricted to so-called regular datatypes. Recent work by R. Bird and L. Meertens [3] on the semantics of non-regular or nested datatypes suggests that an extension to general datatypes is not entirely straightforward. Here we propose an alternative that extends polytypism to arbitrary datatypes, including nested datatypes and mutually recursive datatypes. The central idea is to use rational trees over a suitable set of functor symbols as type arguments for polytypic functions. Besides covering a wider range of types the approach is also simpler and technically less involving than previous ones. We present several examples of polytypic functions, among others polytypic reduction and polytypic equality. The presentation assumes some background in functional and in polytypic programming. A basic knowledge of monads is required for some of the examples.


Keywords: Functional programming, generic programming, nested datatypes, rational trees, reductions.

## 1 Introduction

A polytypic function is a function that is defined by induction on the structure of types. The archetypical example of a polytypic function is size $:: f a \rightarrow I n t$, which counts the number of values of type $a$ in a given value of type $f a$. The function size can sensibly be defined for each polymorphic type and it is usually a tiresome, routine matter to do so. A polytypic programming language allows to program size once and for all times. The specialization of size to concrete instances of $f$ is then handled automatically by the system.

Polytypic programming is usually based on the initial algebra semantics of datatypes. To illustrate, consider the following definition of polymorphic lists.

$$
\text { data List } a=1+a \times \text { List } a
$$

The meaning of List $a$ is given by the initial $F_{a}$-algebra of the functor $F_{a}(b)=F(a, b)=1+a \times b$. The initial algebra can be seen as the least solution of the equation List $a=F(a$, List $a)$. The initial algebra approach, however, has its limitations. It fails, for example, to give a meaning to so-called non-regular or nested datatypes such as the type of perfectly balanced, binary leaf trees [9]

$$
\text { data Perfect } a=a+\operatorname{Perfect}(a \times a)
$$

[^0]Since the recursive call of Perfect on the right-hand side is not a copy of the declared type on the left-hand side, the equation cannot be rewritten into the form Perfect $a=G(a$, Perfect $a)$ for some $G$.

A way out of this dilemma is to consider initial algebras of higher-order functors [3]. If we lift coproduct $(+)$ and product $(\times)$ to functors, $\left(F_{1}+F_{2}\right) T=F_{1} T+F_{2} T$ and $\left(F_{1} \times F_{2}\right) T=F_{1} T \times F_{2} T$, the above type definitions can be rewritten as functor equations:

$$
\begin{aligned}
& \text { List }=K 1+I d \times \text { List } \\
& \text { Perfect }
\end{aligned}=I d+\text { Perfect } \cdot(I d \times I d),
$$

where $K T$ is the constant functor, $I d$ is the identity functor, and $(\cdot)$ denotes functor composition. The meaning of List and Perfect can now be defined as the initial algebra of the associated higher-order functor. While this approach shares some of the elegance and ease of the first-order approach, it also has its drawbacks. It appears that the associated fold-operations, which are at the heart of polytypic programming, are limited in expressibility. The crucial point is that fold operates on natural transformations, ie it takes polymorphic functions to polymorphic functions. For instance, the fold operator on Perfect takes a function of type $\forall a \cdot a+f(a \times a) \rightarrow f a$ to a function of type $\forall a$.Perfect $a \rightarrow f a$ for some fixed $f$. This is, however, too restrictive for many applications, for instance, for summing up a tree of integers. Therefore, it is at least questionable whether initial algebras of higher-order functors can serve as a viable basis for polytypism on nested datatypes.

Back to the first-order case. In a polytypic language the function size $:: f a \rightarrow$ Int is parametrised by the functor $f$ and is defined by induction on the structure of $f$. As an aside, since size is parametrised by a functor, we will qualify size more precisely as a polyfunctorial function. The qualifier polytypic will be used as a general term for functions that are parametrised by functors of arbitrary arity. Now, inspired by the initial algebra semantics the structure of functors is usually given by the following grammar, see [15] or [12].

$$
\begin{aligned}
B & =K T|F s t| S n d|B+B| B \times B \mid F \cdot B \\
F & =\mu B
\end{aligned}
$$

The non-terminal $B$ generates the language of bifunctors. By $\mu B$ we denote the unary functor $F$ given as the least solution of the equation $F a=B(a, F a)$. The functor $F=\mu B$ is also known as a type functor. This representation entails that a non-recursive, polymorphic functor $F$ is modelled by $\mu B$ with $B(a, b)=F a$, whereas a non-polymorphic, recursive datatype induced by a functor $F$ is modelled by $\mu B$ with $B(a, b)=$ $F b$. Thus, $\mu(K 1+F s t)$ encodes the datatype Maybe and $\mu(K 1+S n d)$ encodes the datatype of Peano numerals.

One can reasonably argue that the definition of unary functors via minimalization of bifunctors is not the most direct way to go. An alternative that we explore in this article is to define functor expressions as rational trees [6] over the following grammar of unary functors.

$$
F=K T|I d| F+F|F \times F| F \cdot F
$$

This approach is, of course, inspired by the way types are introduced in most functional programming languages. Type definitions usually take the form of recursion equations. If we interpret these equations purely syntactically, each equation defines a unique rational tree. Recall that a rational (or regular) tree is an infinite tree that has only a finite number of subtrees. Fig. 1 displays the rational trees defined by the type equations above. Note that the pictorial representation already employs the defining property of


## Perfect

Fig. 1: Types interpreted as rational trees.
rational trees. Since the set of subtrees is finite, we can always draw a rational tree as a finite tree with additional back or cross edges.

The major difference to previous approaches lies in the use of infinite instead of finite trees as type arguments for polytypic functions. This change is not as problematic as one might think at first sight. For instance, we can still define polytypic functions recursively and prove polytypic properties inductively. Of course, to make things work we must impose the usual conditions: functions must be continuous and properties must be chain complete. In essence this means that the class of functors is itself modelled by a non-strict datatype as opposed to an inductive datatype. We could even consider functors given by arbitrary infinite trees. The focus on rational trees is, however, necessary for practical considerations. It guarantees that the specialization of polytypic functions always terminates.

The rest of this article is organized as follows. Sec. 2 introduces rational trees and functor expressions. Sec. 3 and Sec. 4 give several examples of polyfunctorial functions, among others a polytypic map and polytypic reduction. We will see that nested datatypes add an interesting new dimension to polytypic programming. For instance, efficiency becomes a concern: a straightforward implementation of size has a quadratic running time for some nested datatypes. Improving its running time makes a nice example in polytypic program derivation. Sec. 5 extends the approach to $n$-ary functors and presents further examples, among others polytypic equality and a polytypic monadic map. This section requires a basic knowledge of monads. Finally, Sec. 6 reviews related work and points out directions for future work.

## 2 Functor expressions

There are several ways to represent rational trees, see, for instance, [6, Sec. 4]. The most obvious and, in fact, the most convenient way is to use systems of recursion equations. Let $\Sigma=\bigcup_{n \geqslant 0} \Sigma_{n}$ be a set of function symbols and $X$ be a set of variables, we denote by $T(\Sigma, X)$ the set of first-order terms over $\Sigma$ and $X$. A system of recursion equations over $\Sigma$ is of the form $\left\{x_{1}=t_{1}, \ldots, x_{n}=t_{n}\right\}$ with $t_{i} \in T(\Sigma, X)$, $X=\left\{x_{1}, \ldots, x_{n}\right\}$, and $x_{i} \neq x_{j}$ for $i \neq j$. The elements of $X$ are termed recursion variables.

A system of recursion equations is in canonical form if the right-hand side of each equation is of the form $f\left(x_{1}, \ldots, x_{n}\right)$ where $f \in \Sigma_{n}$ is an $n$-ary function symbol and the $x_{i}$ are recursion variables. Each system can be transformed into an equivalent system that is in canonical form. For instance, the system $\{x=I d+x \cdot(I d \times I d)\}$ has the canonical form $\left\{x=x_{1}+x_{2}, x_{1}=I d, x_{2}=x \cdot x_{3}, x_{3}=I d \times I d\right\}$. Note that the canonicalization introduces additional recursion variables. Furthermore, we tacitly assume that an equation of the form $x=x$ is replaced by $x=\Omega$ where $\Omega$ is a new nullary function symbol representing the 'bottom' tree.

It is well-known that each canonical system of recursion equations has a unique solution in the realm
of rational trees. An unrestricted system has in general only a least solution. Each tree is, for instance, a solution of the trivial system $\{x=x\}$.

Now, a functor tree is a rational tree over the following set of 'functor' symbols

$$
F=K T|I d| F+F|F \times F| F \cdot F
$$

ie $\Sigma=\Sigma_{0} \cup \Sigma_{2}$ with $\Sigma_{0}=\{K t \mid t \in T\} \cup\{I d\}$ and $\Sigma_{2}=\{+, \times, \cdot\}$. We agree upon that $(\cdot)$ binds more tightly than $(\times)$, which in turn takes precedence over $(+)$. For instance, $F+G \times H \cdot H$ means $F+(G \times(H \cdot H))$.

Let us consider some examples. Finite functor trees correspond to so-called polynomial functors.

$$
\begin{array}{ll}
\Delta & =I d \times I d \\
\text { Maybe } & =K 1+I d
\end{array}
$$

The functor $\Delta$ is called the diagonal or square functor, Maybe $a$ is the type of optional values of type $a$.
Let us call a functor composition $F \cdot G$ non-trivial if neither $F$ nor $G$ equals the identity functor. ${ }^{\ddagger}$ Possibly infinite functor trees where cycles only pass through the right-hand branches of non-trivial functor compositions are known as regular functors.

$$
\begin{aligned}
\text { List } & =K 1+I d \times \text { List } \\
\text { Tree } & =I d+\Delta \cdot \text { Tree } \\
\text { Rose } & =I d \times \text { List } \cdot \text { Rose }
\end{aligned}
$$

The functor List corresponds to the ubiquitous datatype of polymorphic lists, Tree encompasses polymorphic, binary leaf trees, and Rose is the datatype of multi-way branching trees.

If cycles pass through the left-hand branches of non-trivial functor compositions (or through both branches), we have non-regular functors.

$$
\begin{aligned}
\text { Perfect } & =I d+\text { Perfect } \cdot \Delta \\
\text { Nest } & =K 1+I d \times \text { Nest } \cdot \Delta \\
\text { Bush } & =K 1+I d \times \text { Bush } \cdot \text { Bush }
\end{aligned}
$$

The meaning of these functor expressions becomes more intelligible if we unroll the definitions a few steps and massage the result using the following laws.

$$
\begin{align*}
K T \cdot F & =K T  \tag{1}\\
I d \cdot F & =F  \tag{2}\\
F \cdot I d & =F  \tag{3}\\
\left(F_{1}+F_{2}\right) \cdot G & =F_{1} \cdot G+F_{2} \cdot G  \tag{4}\\
\left(F_{1} \times F_{2}\right) \cdot G & =F_{1} \cdot G \times F_{2} \cdot G  \tag{5}\\
\left(F_{1} \cdot F_{2}\right) \cdot F_{3} & =F_{1} \cdot\left(F_{2} \cdot F_{3}\right) \tag{6}
\end{align*}
$$

Unrolling Perfect yields

$$
\text { Perfect }=I d+\left(\Delta+\left(\Delta^{2}+\left(\Delta^{3}+\cdots\right)\right)\right)
$$

[^1]where $F^{n}$ is given by $F^{0}=I d$ and $F^{n+1}=F \cdot F^{n}$. If we interpret $\Delta^{n}$ as the type of perfectly balanced, binary leaf trees of height $n$, we have that Perfect comprises perfect trees of arbitrary height.

The functor Nest has a similar reading.

$$
\text { Nest }=K 1+I d \times\left(K 1+\Delta \times\left(K 1+\Delta^{2} \times\left(K 1+\Delta^{3} \times \cdots\right)\right)\right)
$$

If we compare Nest to

$$
\text { List }=K 1+I d \times(K 1+I d \times(K 1+I d \times(K 1+I d \times \cdots)))
$$

we see that Nest comprises 'lists' whose $i$-th element is a perfect tree of height $i$. Alternatively, we may view values of type Nest as node-oriented perfect trees, where the $i$-th list element describes the sequence of labels at depth $i$.

Partially unrolling Bush yields

$$
\text { Bush }=K 1+I d \times\left(K 1+B u s h \times\left(K 1+B_{1} \operatorname{ush}^{2} \times\left(K 1+\text { Bush }^{3} \times \cdots\right)\right)\right)
$$

Thus, Bush contains 'lists' whose $i$-th element is a member of Bush ${ }^{i}$. A truly bewildering form of recursion.

Interestingly, the laws above can be used to eliminate functor composition from the definitions of regular functors. Consider the definition of rose trees, which contains the composition List•Rose. Introducing a new functor for the composition, say, Forest we obtain

$$
\begin{aligned}
& \text { Rose }^{\prime}=I d \times \text { Forest }^{\prime} \\
& \text { Forest }=K 1+\text { Rose }^{\prime} \times \text { Forest }
\end{aligned}
$$

Since both types, Rose and Rose $^{\prime}$, have the same structure, they are equivalent from a polytypic perspective. This statement can be made precise if we interpret type equations as algebraic equations [6, Sec. 5.1]. Then, both Rose and Rose ${ }^{\prime}$ indeed denote the same rational tree. This implies, in particular, that care must be taken to ensure that polytypic functions behave the same on both definitions (see Sec. 3). As an aside, note that mutually recursive definitions like the two above are covered by recursion equations in a natural way.

## 3 Polytypic map

Our first example of a polytypic function is the function map, which describes the action of a functor on arrows (ie functions). This is, of course, not a coincidence. As we shall see, map is an important building block for virtually all polytypic functions.

To define map we make use of the following auxiliary functions which, as a matter of fact, establish
$(+)$ and $(\times)$ as bifunctors. ${ }^{\S}$

$$
\begin{array}{ll}
\left(f_{1} \nabla f_{2}\right)\left(\text { inl } a_{1}\right) & =f_{1} a_{1} \\
\left(f_{1} \nabla f_{2}\right)\left(\text { inr } a_{2}\right) & =f_{2} a_{2} \\
f_{1}+f_{2} & =\left(\text { inl } \circ f_{1}\right) \nabla\left(\text { inr } \circ f_{2}\right) \\
\left(f_{1} \Delta f_{2}\right) a & =\left(f_{1} a, f_{2} a\right) \\
\text { outl }\left(a_{1}, a_{2}\right) & =a_{1} \\
\text { outr }\left(a_{1}, a_{2}\right) & =a_{2} \\
f_{1} \times f_{2} & =\left(f_{1} \circ \text { outl }\right) \Delta\left(f_{2} \circ \text { outr }\right)
\end{array}
$$

The polytypic map is then given by the following definition.

$$
\begin{array}{ll}
\operatorname{map}\langle f\rangle & :(a \rightarrow b) \rightarrow(f a \rightarrow f b) \\
\operatorname{map}\langle K t\rangle \varphi & =\operatorname{id} \\
\operatorname{map}\langle I d\rangle \varphi & =\varphi \\
\operatorname{map}\langle f+g\rangle \varphi & =\operatorname{map}\langle f\rangle \varphi+\operatorname{map}\langle g\rangle \varphi \\
\operatorname{map}\langle f \times g\rangle \varphi & =\operatorname{map}\langle f\rangle \varphi \times \operatorname{map}\langle g\rangle \varphi \\
\operatorname{map}\langle f \cdot g\rangle \varphi & =\operatorname{map}\langle f\rangle(\operatorname{map}\langle g\rangle \varphi)
\end{array}
$$

The first line specifies the type of map. The notation $\operatorname{map}\langle f\rangle$ has been chosen to emphasize that map is parametrised by a functor. Polytypic functions are always written using angle brackets, which makes it easy to distinguish them from ordinary functions.

In general, a polyfunctorial function poly $\langle f\rangle:: \tau(f)$ is given by a set of functions $d_{s}:: \tau\left(f_{1}\right) \times \ldots \times$ $\tau\left(f_{n}\right) \rightarrow \tau\left(s\left(f_{1}, \ldots, f_{n}\right)\right)$, one for each functor symbol $s \in \Sigma$. We usually define the functions implicitly using equations of the form $\operatorname{poly}\left\langle s\left(f_{1}, \ldots, f_{n}\right)\right\rangle=d_{s}\left(\operatorname{poly}\left\langle f_{1}\right\rangle, \ldots, \operatorname{poly}\left\langle f_{n}\right\rangle\right)$. Furthermore, we assume that $d_{\Omega}=\perp$ for the 'bottom' tree $\Omega$. In the example above we have, for instance, $d_{I d}=i d$ and $d_{(\cdot)}\left(m_{1}, m_{2}\right)=$ $m_{1} \circ m_{2}$. This information is sufficient to define a unique function poly$\langle f\rangle$ for each functor expression $f$ [6, Prop. 2.4.2]. However, there is one further requirement. The polyfunctorial should be invariant with respect to the functor equations (1), $\ldots$, (6), ie

$$
\begin{aligned}
\operatorname{poly}\langle K T \cdot F\rangle & =\operatorname{poly}\langle K T\rangle \\
\operatorname{poly}\langle I d \cdot F\rangle & =\operatorname{poly}\langle F\rangle \\
\operatorname{poly}\langle F \cdot I d\rangle & =\operatorname{poly}\langle F\rangle \\
\operatorname{poly}\left\langle\left(F_{1}+F_{2}\right) \cdot G\right\rangle & =\operatorname{poly}\left\langle F_{1} \cdot G+F_{2} \cdot G\right\rangle \\
\operatorname{poly}\left\langle\left(F_{1} \times F_{2}\right) \cdot G\right\rangle & =\operatorname{poly}\left\langle F_{1} \cdot G \times F_{2} \cdot G\right\rangle \\
\operatorname{poly}\left\langle\left(F_{1} \cdot F_{2}\right) \cdot F_{3}\right\rangle & =\operatorname{poly}\left\langle F_{1} \cdot\left(F_{2} \cdot F_{3}\right)\right\rangle .
\end{aligned}
$$

If poly $\langle f\rangle$ violates one of these constraints, then it is sensitive to the form in which $f$ is written, a situation which is clearly undesirable. For instance, poly $\langle$ Rose $\rangle$ and poly $\left\langle\right.$ Rose $\left.^{\prime}\right\rangle$ should be identical since Rose and Rose ${ }^{\prime}$ define the same functor. It is immediate from its definition that $\operatorname{map}\langle f\rangle$ satisfies these conditions.

[^2]From the definition of $\operatorname{map}\langle f\rangle$ we can derive specializations for different instances of $f$. Here is the familiar definition of map on List.

$$
\operatorname{map}\langle\text { List }\rangle \varphi=i d+\varphi \times \operatorname{map}\langle\text { List }\rangle \varphi
$$

Note that the process of specialization always terminates since the 'functor argument' is given by a rational tree, which has only a finite set of subtrees. Now, if we specialize map for non-regular functors something interesting happens.

$$
\operatorname{map}\langle\text { Perfect }\rangle \varphi=\varphi+\operatorname{map}\langle\text { Perfect }\rangle(\varphi \times \varphi)
$$

The type of map $\langle$ Perfect $\rangle$ is $(a \rightarrow b) \rightarrow($ Perfect $a \rightarrow$ Perfect $b)$. The recursive call on the right-hand side, however, has type $(\Delta a \rightarrow \Delta b) \rightarrow(\operatorname{Perfect}(\Delta a) \rightarrow \operatorname{Perfect}(\Delta b))$, which is a substitution instance of map $\langle$ Perfect $\rangle$ 's type. This means that map $\langle$ Perfect $\rangle$ is a so-called polymorphically recursive function [19]. It should be noted that the Hindley-Milner type system, which underlies most of today's functional programming languages, does not allow polymorphic recursion. Furthermore, a suitable extension of the system has been shown to be undecidable [8]. The functional programming language Haskell [21] allows polymorphic recursion only if an explicit type signature is provided for the function. We will assume henceforth that polymorphic recursion is supported by the underlying programming language.

In general, the specialization of a polytypic function poly $\langle f\rangle$ for a given instance of $f$ is defined as follows. Assume that the functor is given by a canonical system of recursion equations. For each equation $f=s\left(f_{1}, \ldots, f_{n}\right)$ a function definition of the form $\operatorname{poly}\langle f\rangle=d_{s}\left(\operatorname{poly}\left\langle f_{1}\right\rangle, \ldots, \operatorname{poly}\left\langle f_{n}\right\rangle\right)$ is generated. It is straightforward to generalize the process of specialization to arbitrary systems of recursion equations.

To prove properties of polytypic function we can employ the principle of fixpoint induction. If $P$ is a chain complete property of functor trees, it suffices to show

$$
\begin{aligned}
& P(\Omega) \\
& P(K t) \\
& P(I d) \\
& P(F) \wedge P(G) \Longrightarrow P(F+G) \\
& P(F) \wedge P(G) \Longrightarrow P(F \times G) \\
& P(F) \wedge P(G) \Longrightarrow P(F \cdot G) .
\end{aligned}
$$

Using a simple fixpoint induction we can prove, for instance, the following functorial properties of $\operatorname{map}\langle f\rangle$.

$$
\begin{aligned}
\operatorname{map}\langle f\rangle i d & =\text { id } \\
\operatorname{map}\langle f\rangle(\varphi \circ \psi) & =\operatorname{map}\langle f\rangle \varphi \circ \operatorname{map}\langle f\rangle \psi
\end{aligned}
$$

The proof for coproduct and product relies on the fact that $(+)$ and $(\times)$ are themselves bifunctors.

$$
\begin{align*}
& \left(f_{1}+f_{2}\right) \circ\left(g_{1}+g_{2}\right)=\left(f_{1} \circ g_{1}\right)+\left(f_{2} \circ g_{2}\right)  \tag{7}\\
& \left(f_{1} \times f_{2}\right) \circ\left(g_{1} \times g_{2}\right)=\left(f_{1} \circ g_{1}\right) \times\left(f_{2} \circ g_{2}\right) \tag{8}
\end{align*}
$$

Only the proof of $\operatorname{map}\langle\Omega\rangle$ id $=i d$ requires a bit of fudging. We have that $\operatorname{map}\langle\Omega\rangle \varphi=\lambda a \rightarrow \perp$ so we must in effect show that $\lambda a \rightarrow \perp=i d$. This equation holds, however, since $\Omega$ accommodates only the bottom element.

## 4 Polytypic reduction

A reduction is a function of type $f a \rightarrow a$ that collapses a structure of values of type $a$ into a single value of type $a$. Because of its destructive nature reductions are also known as crushes. The archetypical example of a reduction is the function that sums a structure of integers, for instance, a list or a tree of integers. It is well-known that reductions can be defined completely generically for all regular functors [15]. In the sequel we show how to generalize reductions to non-regular functors. The ability to define reductions on nested datatypes is of some importance since it is not possible to sum a nested datatype using a fold. Note that this implies that reductions are in a sense more general than folds. They are, however, also less general since, for instance, mapping functions on regular functors can be defined using folds, but cannot be expressed in the form of a crush. Thus, reductions [15] and folds [14] are different, incomparable generalizations of the classic reduction operator (/) on join-lists [5]. For a more detailed comparison we refer the interested reader to [15].

To define a reduction we require two ingredients: a value $e:: a$ and a binary operation op $:: \Delta a \rightarrow a$. Usually but not necessarily $e$ is the neutral element of $o p$.

$$
\begin{array}{ll}
\operatorname{reduce}\langle f\rangle & :: \quad a \rightarrow(\Delta a \rightarrow a) \rightarrow(f a \rightarrow a) \\
\operatorname{reduce}\langle f\rangle \text { e op } & = \\
\text { whered }\langle f\rangle \\
\text { red }\langle K t\rangle & = \\
\operatorname{red}\langle I d\rangle & =\text { const e } \\
\operatorname{red}\langle f+g\rangle & =\operatorname{red}\langle f\rangle \nabla \operatorname{red}\langle g\rangle \\
\operatorname{red}\langle f \times g\rangle & =\operatorname{op} \circ(\operatorname{red}\langle f\rangle \times \operatorname{red}\langle g\rangle) \\
\operatorname{red}\langle f \cdot g\rangle & =\operatorname{red}\langle f\rangle \circ \operatorname{map}\langle f\rangle(\operatorname{red}\langle g\rangle)
\end{array}
$$

The definition coincides with the one given by L. Meertens [15], the only difference is that the treatment of recursion is implicit-the specialization automatically takes care of recursion-rather than explicit. This alone suffices to define reduce $\langle f\rangle$ for all datatypes including nested datatypes such as Perfect.

The most interesting equation is probably the last one: to reduce a value of type $f(g a)$, the reduction red $\langle g\rangle$ is first mapped on $f$ to give a value of type $f a$, which is then reduced to a value of type $a$. To see reduce $\langle f\rangle$ in action let us specialize the definition to the type of perfect trees (note that $r e d\langle\Delta\rangle=o p$ ).

$$
\operatorname{red}\langle\text { Perfect }\rangle=i d \nabla \operatorname{red}\langle\text { Perfect }\rangle \circ \operatorname{map}\langle\text { Perfect }\rangle \text { op }
$$

Assume that we want to reduce a perfect tree of height $n$. The function map $\langle$ Perfect $\rangle$ op, which has type Perfect $(\Delta a) \rightarrow$ Perfect $a$, takes a tree of height $i+1$ to a tree of height $i$, which is then reduced by a recursive call to red $\langle$ Perfect $\rangle$. After $n$ iterations we obtain the desired value of type $a$. What about red $\langle$ Perfect $\rangle$ 's running time? Let us assume that $o p$ is a constant-time operation. The call map $\langle$ Perfect $\rangle$ op then takes time proportional to the size of the tree. Since the size of the tree is halved in each step, we obtain a running time of

$$
2^{n}+2^{n-1}+\cdots+2+1=\Theta\left(2^{n}\right)
$$

Thus, the red $\langle$ Perfect $\rangle$ takes time proportional to the size of the tree. Does this hold in general? Unfortunately not, as the following example shows.

$$
\begin{aligned}
\text { Maybe } & =\text { Nothing }(\text { K1 })+\text { Just Id } \\
\text { Tower } & =\text { End Id }+ \text { Recurse }(\text { Tower } \cdot \text { Maybe })
\end{aligned}
$$

We have added fancy names for the injection functions to make the examples more readable. Now, elements of type Tower are either of the form Recurse ${ }^{n}$ (End (Just ${ }^{m}$ Nothing)) with $m<n$ or of the form Recurse $^{n}\left(\right.$ End $^{\left.\left(\text {Just }^{n} a\right)\right) \text {. The reduction on Tower is given by the following equation. }}$

$$
\operatorname{red}\langle\text { Tower }\rangle=i d \nabla \text { red }\langle\text { Tower }\rangle \circ \operatorname{map}\langle\text { Tower }\rangle(\text { const } e \nabla \text { id })
$$

The crush of Recurse $^{n}\left(E n d\left(J u s t^{n} a\right)\right)$ proceeds essentially as before: map $\langle$ Tower $\rangle$ (conste $\nabla$ id) maps the value Recurse ${ }^{i}\left(E n d\left(\right.\right.$ Just $\left.\left.^{i+1} a\right)\right)$ to Recurse $^{i}\left(E n d\left(\right.\right.$ Just $\left.\left.^{i} a\right)\right)$, which is then reduced by a recursive call to red $\langle$ Tower $\rangle$. The major difference to the preceding example is that in each step the size of the argument is only decreased by a constant amount. Consequently, we have a total running time of

$$
n+n-1+\cdots+2+1=\Theta\left(n^{2}\right)
$$

which shows that red $\langle$ Tower $\rangle$ 's running time is quadratic with respect to the size of its argument. Interestingly, the efficiency of reduce $\langle f\rangle$ is not a problem if $f$ is a regular functor. In this case reduce $\langle f\rangle$ always takes time linear to the size of the crushed structure. The argument roughly runs as follows: Recall that each regular functor has an equivalent, composition-free definition. If functor composition is not used, red $\langle f\rangle$ clearly runs in linear time. The asymptotic running time of $r e d\langle f\rangle$ is, however, the same for equivalent functor definitions.

Fortunately, it is straightforward to improve the efficiency of reduce $\langle f\rangle$. We simply define a function that combines a reduction with a map, ie we seek for a function redmap $\langle f\rangle$ that satisfies

$$
\begin{aligned}
\operatorname{redmap}\langle f\rangle \varphi & =\operatorname{red}\langle f\rangle \circ \operatorname{map}\langle f\rangle \varphi, \\
\operatorname{red}\langle f\rangle & =\operatorname{redmap}\langle f\rangle i d .
\end{aligned}
$$

This idiom is, in fact, a very old one. It appears, for instance, in [5] where it is shown that each homomorphism on lists (ie each fold) can be expressed in this form. The derivation of redmap $\langle f\rangle$ is a simple exercise in program calculation and proceeds almost mechanically. For the two base cases we have

$$
\begin{aligned}
& \text { redmap }\langle K t\rangle \varphi=\operatorname{red}\langle K t\rangle \circ \operatorname{map}\langle K t\rangle \varphi=\text { const e } \circ \text { id }=\text { const } e, \\
& \operatorname{redmap}\langle I d\rangle \varphi=\operatorname{red}\langle I d\rangle \circ \operatorname{map}\langle I d\rangle \varphi=\text { id } \circ \varphi=\varphi
\end{aligned}
$$

The derivation for coproducts and products rests on their properties as bifunctors, ie on equations (7) and (8).

$$
\begin{aligned}
\operatorname{redmap}\langle f+g\rangle \varphi & =\operatorname{red}\langle f+g\rangle \circ \operatorname{map}\langle f+g\rangle \varphi \\
& =(\operatorname{red}\langle f\rangle \nabla \operatorname{red}\langle g\rangle) \circ(\operatorname{map}\langle f\rangle \varphi+\operatorname{map}\langle g\rangle \varphi) \\
& =(\operatorname{red}\langle f\rangle \circ \operatorname{map}\langle f\rangle \varphi) \nabla(\operatorname{red}\langle g\rangle \circ \operatorname{map}\langle g\rangle \varphi) \\
& =\operatorname{redmap}\langle f\rangle \varphi \nabla \operatorname{redmap}\langle g\rangle \varphi \\
\operatorname{redmap}\langle f \times g\rangle \varphi & =\operatorname{red}\langle f \times g\rangle \circ \operatorname{map}\langle f \times g\rangle \varphi \\
& =\operatorname{op} \circ(\operatorname{red}\langle f\rangle \times \operatorname{red}\langle g\rangle) \circ(\operatorname{map}\langle f\rangle \varphi \times \operatorname{map}\langle g\rangle \varphi) \\
& =\operatorname{op} \circ((\operatorname{red}\langle f\rangle \circ \operatorname{map}\langle f\rangle \varphi) \times(\operatorname{red}\langle g\rangle \circ \operatorname{map}\langle g\rangle \varphi)) \\
& =\operatorname{op} \circ(\operatorname{redmap}\langle f\rangle \varphi \times \operatorname{redmap}\langle g\rangle \varphi)
\end{aligned}
$$

And finally, for the composition of functors we obtain

$$
\begin{aligned}
\operatorname{redmap}\langle f \cdot g\rangle \varphi & =\operatorname{red}\langle\langle\cdot g\rangle \circ \operatorname{map}\langle f \cdot g\rangle \varphi \\
& =\operatorname{red}\langle f\rangle \circ \operatorname{map}\langle f\rangle(\operatorname{red}\langle g\rangle) \circ \operatorname{map}\langle f\rangle(\operatorname{map}\langle g\rangle \varphi) \\
& =\operatorname{red}\langle f\rangle \circ \operatorname{map}\langle f\rangle(\operatorname{red}\langle g\rangle \circ \operatorname{map}\langle g\rangle \varphi) \\
& =\operatorname{redmap}\langle f\rangle(\operatorname{redmap}\langle g\rangle \varphi),
\end{aligned}
$$

```
\(\operatorname{sum}\langle f\rangle \quad:: \quad(\) Num \(n) \Rightarrow f n \rightarrow n\)
\(\operatorname{sum}\langle f\rangle=\) reduce \(\langle f\rangle 0(+)\)
and \(\langle f\rangle \quad:: \quad f\) Bool \(\rightarrow\) Bool
and \(\langle f\rangle \quad=\) reduce \(\langle f\rangle\) True \((\wedge)\)
minimum \(\langle f\rangle \quad:: \quad\) (Bounded \(a\), Ord \(a) \Rightarrow f a \rightarrow a\)
minimum \(\langle f\rangle=\) reduce \(\langle f\rangle\) maxBound min
size \(\langle f\rangle \quad:: \quad(\) Num \(n) \Rightarrow f a \rightarrow n\)
size \(\langle f\rangle=\) reducemap \(\langle f\rangle 0(+)(\) const 1\()\)
all \(\langle f\rangle \quad:: \quad(a \rightarrow\) Bool \() \rightarrow(f a \rightarrow\) Bool \()\)
\(\operatorname{all}\langle f\rangle p=\) reducemap \(\langle f\rangle\) True \((\wedge) p\)
flatten \(\langle f\rangle \quad:: \quad f a \rightarrow\) List \(a\)
flatten \(\langle f\rangle=\) reducemap \(\langle f\rangle[](+)\) wrap where wrap \(a=[a]\)
```

Fig. 2: Examples of reductions.
which shows that we succeeded in eliminating the annoying call to map. Apart from improving the efficiency of reduce $\langle f\rangle$ the synthesized function is also interesting in its own right since it captures a common pattern of recursion.

```
reduce \(\langle f\rangle\) e op \(\quad=\) reducemap \(\langle f\rangle\) e op id
reducemap \(\langle f\rangle \quad:: \quad a \rightarrow(\Delta a \rightarrow a) \rightarrow(b \rightarrow a) \rightarrow(f b \rightarrow a)\)
reducemap \(\langle f\rangle\) e op \(=\) redmap \(\langle f\rangle\)
    where
    redmap \(\langle K t\rangle \varphi=\) const \(e\)
    redmap \(\langle I d\rangle \varphi=\varphi\)
    redmap \(\langle f+g\rangle \varphi=\operatorname{redmap}\langle f\rangle \varphi \nabla\) redmap \(\langle g\rangle \varphi\)
    redmap \(\langle f \times g\rangle \varphi=o p \circ(\operatorname{redmap}\langle f\rangle \varphi \times \operatorname{redmap}\langle g\rangle \varphi)\)
    redmap \(\langle f \cdot g\rangle \varphi=\operatorname{redmap}\langle f\rangle(\operatorname{redmap}\langle g\rangle \varphi)\)
```

Let us again specialize the definition to the type of perfect trees.

$$
\text { redmap }\langle\text { Perfect }\rangle \varphi=\varphi \nabla \text { redmap }\langle\text { Perfect }\rangle(o p \circ(\varphi \times \varphi))
$$

It is interesting if not revealing to contrast the two definitions of reductions on perfect trees. The first one, red $\langle$ Perfect $\rangle$, essentially proceeds bottom-up. In each step the 'nodes' (ie pairs) on the lowest level are reduced. This step is repeated until the root is reached. By contrast, redmap $\langle$ Perfect $\rangle$ operates in two stages: first a suitable reduction function is constructed, which then reduces the perfect tree in a single top-down pass. Clearly, the latter procedure is more efficient than the former.

Fig. 2 lists some typical applications of reduce $\langle f\rangle$ and reducemap $\langle f\rangle$. Further examples can be found, for instance, in [15] or [11].

Polytypic reduction satisfies a fusion law analogous to the fusion law for folds [15].

```
        \(h \circ\) reducemap \(\langle f\rangle\) e op \(\varphi=\) reducemap \(\langle f\rangle e^{\prime} o p^{\prime} \varphi^{\prime}\)
\(\Longleftarrow \quad h \circ \perp=\perp\)
\(\wedge \quad h \circ\) const \(e=\) const \(e^{\prime}\)
\(\wedge \quad h \circ o p=o p^{\prime} \circ(h \times h)\)
\(\wedge \quad h \circ \varphi=\varphi^{\prime}\)
```

The law can be shown using a straightforward fixpoint induction, which is left as an exercise to the reader. Instead we apply the fusion law to derive an efficient implementation of size $\langle$ Perfect $\rangle$. A simple consequence of the fusion law is

$$
\text { reducemap }\langle f\rangle 0(+)(\text { const } n)=\text { mult } n \circ \text { reducemap }\langle f\rangle 0(+)(\text { const } 1) \text { where } \text { mult } a b=a * b .
$$

Now, we reason

$$
\begin{aligned}
\text { size }\langle\text { Perfect }\rangle & =\text { reducemap }\langle\text { Perfect }\rangle 0(+)(\text { const } 1) \\
& =\text { const } 1 \nabla \text { reducemap }\langle\text { Perfect }\rangle 0(+)(\text { reducemap }\langle\Delta\rangle 0(+)(\text { const } 1)) \\
& =\text { const } 1 \nabla \text { reducemap }\langle\text { Perfect }\rangle(+)(\text { const } 2) \\
& =\text { const } 1 \nabla \text { mult } 2 \circ \text { size }\langle\text { Perfect }\rangle .
\end{aligned}
$$

Defined this way size $\langle$ Perfect $\rangle$ runs in $\Theta(\log n)$ time.

## 5 Extending the approach to $n$-ary functors

By now we have seen several examples of polyfunctorial functions, ie functions that are parametrised by an unary functor. In this section we extend the approach from unary to $n$-ary functors. It is relatively straightforward to extend functor expressions to the general case: An $n$-ary functor expression is a rational tree over the following set of 'functor' symbols.

$$
\begin{array}{rlr}
F^{(n)}= & K T & \\
& P_{i}^{n} \\
& F^{(n)}+F^{(n)} & (1 \leqslant i \leqslant n) \\
& F^{(n)} \times F^{(n)} & \\
& F^{(k)} \cdot\left(F_{1}^{(n)}, \ldots, F_{k}^{(n)}\right) & (1 \leqslant k)
\end{array}
$$

The superscript in $F^{(n)}$ denotes the arity of the functor. As before, $K T$ denotes the $n$-ary constant functor. The $n$-ary projection functor $P_{i}^{n}$ is given by $P_{i}^{n} \vec{T}=T_{i}$ for $\vec{T}=\left(T_{1}, \ldots, T_{n}\right)$. For $n=1$ and $n=2$ we use the following more familiar names: $I d=P_{1}^{1}, F s t=P_{1}^{2}$, and $\operatorname{Snd}=P_{2}^{2}$. The coproduct and product of $n$-ary functors are defined as usual: $\left(F_{1}+F_{2}\right) \vec{T}=F_{1} \vec{T}+F_{2} \vec{T}$ and $\left(F_{1} \times F_{2}\right) \vec{T}=F_{1} \vec{T} \times F_{2} \vec{T}$. Finally, $F \cdot\left(G_{1}, \ldots, G_{k}\right)$ denotes the composition of the $k$-ary functor $F$ with $k n$-ary functors: $\left(F \cdot\left(G_{1}, \ldots, G_{k}\right)\right) \vec{T}=$ $F\left(G_{1} \vec{T}, \ldots, G_{k} \vec{T}\right)$. We omit the parentheses when $k=1$, ie we write $F \cdot F_{1}$ instead of $F \cdot\left(F_{1}\right)$.

From the definitions of $K T, P_{i}^{n},(+),(\times)$, and $(\cdot)$ we can easily derive the following laws.

$$
\begin{aligned}
K T \cdot\left(F_{1}, \ldots, F_{n}\right) & =K T \\
P_{i}^{n} \cdot\left(F_{1}, \ldots, F_{n}\right) & =F_{i} \\
F \cdot\left(P_{1}^{n}, \ldots, P_{n}^{n}\right) & =F \\
\left(F_{1}+F_{2}\right) \cdot\left(G_{1}, \ldots, G_{n}\right) & =F_{1} \cdot\left(G_{1}, \ldots, G_{n}\right)+F_{2} \cdot\left(G_{1}, \ldots, G_{n}\right) \\
\left(F_{1} \times F_{2}\right) \cdot\left(G_{1}, \ldots, G_{n}\right) & =F_{1} \cdot\left(G_{1}, \ldots, G_{n}\right) \times F_{2} \cdot\left(G_{1}, \ldots, G_{n}\right) \\
\left(F \cdot\left(G_{1}, \ldots, G_{n}\right)\right) \cdot\left(H_{1}, \ldots, H_{o}\right) & =F \cdot\left(G_{1} \cdot\left(H_{1}, \ldots, H_{o}\right), \ldots, G_{m} \cdot\left(H_{1}, \ldots, H_{o}\right)\right)
\end{aligned}
$$

For $n=o=1$ we obtain the laws given in Sec. 2 .
Coproduct and product are the simplest examples of bifunctors.

$$
\begin{aligned}
\text { Coproduct } & =F s t+\text { Snd } \\
\text { Product } & =F s t \times \text { Snd }
\end{aligned}
$$

It is easy to verify that Coproduct $\cdot\left(F_{1}, F_{2}\right)=F_{1}+F_{2}$ and Product $\cdot\left(F_{1}, F_{2}\right)=F_{1} \times F_{2}$, which shows that we could have added $(+)$ and $(\times)$ as constants to $F^{(2)}$. The infix notation is, however, more convenient to use.

External search trees make nice examples of bifunctors. An external search tree of type STab has external nodes (ie leafs) labelled with values of type $a$ and internal nodes (ie branches) labelled with values of type $b$.

$$
\begin{aligned}
\text { Branch } & =F s t \times \text { Snd } \times F s t \\
S T & =F s t+\text { Branch } \cdot(\text { ST }, \text { Snd }) \\
\text { PST } & =F s t+\text { PST } \cdot(\text { Branch }, \text { Snd })
\end{aligned}
$$

External search trees come in two flavours: $S T$ is the standard textbook type while PST is the type of perfect external search trees. Note that $S T$ is right recursive whereas $P S T$ is left recursive. The classification of functors into polynomial, regular, and non-regular functors also carries over to the $n$-ary case. It is easy to see that Branch is a polynomial, ST a regular, and PST a non-regular bifunctor.

### 5.1 Polytypic and polyfunctorial functions

Our first (and our last) example of a polytypic function that is indexed by a nullary functor is polytypic equality. Besides implementing a fundamental operation the example also demonstrates the interaction between polytypic and polyfunctorial functions. Note that the definition of equality is based upon the approach taken in PolyLib [11]. In PolyLib, however, equality is parametrised by an unary functor. Now, to be able to give the definitions in a point-free style, we make use of the auxiliary functions shown in Fig. 3. The first cases of eq $\langle t\rangle$ are straightforward. We assume that the primitive types are 1, Int, and Double and that suitable equality functions for Int and Double are predefined.

$$
\begin{aligned}
& e q\langle t\rangle \quad:: \quad t \times t \rightarrow \text { Bool } \\
& \text { eq }\langle K 1\rangle \quad=\text { const True } \\
& e q\langle\text { KInt }\rangle=\text { eqint } \\
& e q\langle\text { KDouble }\rangle=\text { eqdouble } \\
& e q\left\langle t_{1}+t_{2}\right\rangle=o k\left(e q\left\langle t_{1}\right\rangle \nabla e q\left\langle t_{2}\right\rangle\right) \circ \text { couple } \\
& e q\left\langle t_{1} \times t_{2}\right\rangle=(\wedge) \circ\left(e q\left\langle t_{1}\right\rangle \times e q\left\langle t_{2}\right\rangle\right) \circ \text { transpose }
\end{aligned}
$$

```
\((p \rightarrow f, g) a \quad=\quad\) if \(p a\) then \(f a\) else \(g a\)
couple \(\left(\right.\) inl \(a_{1}\), inl \(\left.b_{1}\right) \quad=\quad \operatorname{Just}\left(\operatorname{inl}\left(a_{1}, b_{1}\right)\right)\)
couple \(\left(\right.\) inl \(a_{1}\), inr \(\left.b_{2}\right)=\) Nothing
couple \(\left(\right.\) inr \(a_{2}\), inl \(\left.b_{1}\right) \quad=\) Nothing
couple (inr \(a_{2}\), inr \(\left.b_{2}\right)=\operatorname{Just}\left(\operatorname{inr}\left(a_{2}, b_{2}\right)\right)\)
transpose \(\left(\left(a_{1}, a_{2}\right),\left(b_{1}, b_{2}\right)\right)=\left(\left(a_{1}, b_{1}\right),\left(a_{2}, b_{2}\right)\right)\)
ok \(\varphi\) Nothing \(=\) False
\(o k \varphi(\) Just \(a) \quad=\quad \varphi a\)
```

Fig. 3: Auxiliary functions for polytypic equality.
It remains to define $e q\langle t\rangle$ for the case that $t$ is a composition of a $k$-ary functor with $k$ nullary functors. To keep the example manageable we confine ourselves to unary functors. How do we proceed if $t$ takes the form $f u$ ? Now, two elements of $f u$ are equal if they have the same shape and the elements of type $u$ at corresponding positions are equal. To bring corresponding elements together we make use of an auxiliary, polyfunctorial function called zip $\langle f\rangle$. As the name indicates, $z i p\langle f\rangle::(f a, f b) \rightarrow \operatorname{Maybe}(f(a, b))$ turns a pair of structures into a structure of pairs. If the structures have not the same shape, zip $\langle f\rangle$ returns Nothing, otherwise it yields Just $z$ where $z$ is the desired structure. Using $z i p\langle f\rangle$ the last case of $e q\langle t\rangle$ can be defined as

$$
e q\langle f \cdot u\rangle=o k(\operatorname{all}\langle f\rangle(e q\langle u\rangle)) \circ z i p\langle f\rangle
$$

which is more or less a translation of the english description above.
The auxiliary function zip $\langle f\rangle$ makes a nice example of polytypic, monadic programming. Before we discuss its definition let us briefly review the basics of monads. For a more in-depth treatment we refer the interested reader to $P$. Wadler's papers [23, 24, 25], which also contain supplementary pointers to relevant work. One can think of a monad as an abstract type for computations. In Haskell monads are captured by the following class declaration.

$$
\begin{aligned}
& \text { class Monad } m \text { where } \\
& \text { return } \quad:: \quad a \rightarrow m a \\
& (\gg)
\end{aligned}:: \quad m a \rightarrow(a \rightarrow m b) \rightarrow m b .
$$

The essential idea of monads is to distinguish between computations and values. This distinction is reflected on the type level: an element of $m a$ represents a computation that yields a value of type $a$. A computation may involve, for instance, state, exceptions, or nondeterminism. The trivial computation that immediately returns the value $a$ is denoted by return $a$. The operator ( $\gg$ ), commonly called 'bind', combines two computations: $m \gg k$ applies $k$ to the result of the computation $m$.

The monadic operations must be related by the following so-called monad laws.

$$
\begin{align*}
\text { return } a \gg k & =k a  \tag{9}\\
m \gg \text { return } & =m  \tag{10}\\
(m \gg k) \gg \ell & =m \gg=(\lambda a \rightarrow k a \gg \ell) \tag{11}
\end{align*}
$$

Roughly speaking return is the neutral element of (>>) and (>>) is associative. The monoidal structure becomes more apparent if the laws are rephrased in terms of the monadic composition, see below.

Haskell supports monadic programming by providing a more readable, first-order syntax for ( $\gg$ ), the so-called do-notation. The syntax and semantics of do-expressions are given by the following identities:

$$
\begin{aligned}
\boldsymbol{d o}\{x \leftarrow m ; e\} & =m \gg=\lambda x \rightarrow \boldsymbol{d o}\{e\} \\
\boldsymbol{d o}\{e\} & =e .
\end{aligned}
$$

Several datatypes have a computational content. For instance, the type Maybe can be used to model exceptions: Just $x$ represents a 'normal' or successful computation yielding the value $x$ while Nothing represents an exceptional or failing computation-zip $\langle f\rangle$ employs Maybe in this sense. The following instance declaration shows how to define return and (>>) for Maybe.

$$
\begin{array}{ll}
\text { instance Monad Maybe where } \\
\begin{aligned}
\text { return } & =\text { Just } \\
\text { Nothing } \gg k & =\text { Nothing } \\
\text { Just } a \gg k & =k a
\end{aligned}
\end{array}
$$

Thus, $m \gg=k$ can be seen as a strict postfix application: if $m$ is an exception, the exception is propagated; if $m$ succeeds, then $k$ is applied to the resulting value.

In the previous examples we have made heavy use of general combining forms such as $(\circ),(+)$, and $(\times)$. The function $z i p\langle f\rangle$ can be defined quite succinctly if we raise these combinators to procedures. A procedure is by definition a function that maps values to computations, ie it is a function of type $a \rightarrow m b$ where $m$ is a monad.

$$
\begin{array}{ll}
\left(h_{1} \odot h_{2}\right) a & =\mathbf{d o}\left\{b \leftarrow h_{2} a ; h_{1} b\right\} \\
\left(h_{1} \otimes h_{2}\right)\left(a_{1}, a_{2}\right) & =\text { do }\left\{b_{1} \leftarrow h_{1} a_{1} ; b_{2} \leftarrow h_{2} a_{2} ; \text { return }\left(b_{1}, b_{2}\right)\right\} \\
\left(h_{1} \oplus h_{2}\right)\left(\text { inl } a_{1}\right) & =\text { do }\left\{b_{1} \leftarrow h_{1} a_{1} ; \text { return }\left(\text { inl } b_{1}\right)\right\} \\
\left(h_{1} \oplus h_{2}\right)\left(\text { inr } a_{2}\right) & =\text { do }\left\{b_{2} \leftarrow h_{2} a_{2} ; \text { return }\left(\text { inr } b_{2}\right)\right\}
\end{array}
$$

While the definitions for $(\odot)$ and $(\oplus)$ are inevitable, there is a choice to be made in the case of $(\otimes)$. The two computations $h_{1} a_{1}$ and $h_{2} a_{2}$ can be sequenced in two possible ways, either $h_{1} a_{1}$ before $h_{2} a_{2}$ or vice versa. Fortunately, the two definitions coincide for $m=$ Maybe. ${ }^{\text {II }}$ From the definitions above we can easily derive the following equations:

$$
\begin{align*}
f \odot(g \circ h) & =(f \odot g) \circ h  \tag{12}\\
f \odot r e t u r n & =f  \tag{13}\\
\text { return } \odot f & =f  \tag{14}\\
f \odot(g \odot h) & =(f \odot g) \odot h  \tag{15}\\
\left(f_{1} \oplus f_{2}\right) \odot\left(g_{1} \oplus g_{2}\right) & =\left(f_{1} \odot g_{1}\right) \oplus\left(f_{2} \odot g_{2}\right)  \tag{16}\\
\left(f_{1} \otimes f_{2}\right) \odot\left(g_{1} \otimes g_{2}\right) & =\left(f_{1} \odot g_{1}\right) \otimes\left(f_{2} \odot g_{2}\right) \quad \text { if } m \text { is commutative } \tag{17}
\end{align*}
$$

[^3]Note that equations (13), (14), and (15) are the monad laws stated in terms of the monadic composition (@). These equations furthermore show that procedures (for a fixed $m$ ) form the morphisms of a category, the so-called Kleisli category, where the identity is return and the composition is (©). The last equation only holds for so-called commutative monads that satisfy

$$
\text { do }\left\{a_{1} \leftarrow m_{1} ; a_{2} \leftarrow m_{2} ; \text { return }\left(a_{1}, a_{2}\right)\right\}=\text { do }\left\{a_{2} \leftarrow m_{2} ; a_{1} \leftarrow m_{1} ; \text { return }\left(a_{1}, a_{2}\right)\right\} .
$$

For instance, the identity monad, the Maybe monad, and reader monads all have this property. On the other hand, the list monad, the state monads, and the $I O$ monad are not commutative. This implies that $(\times)$ is not a bifunctor in the corresponding Kleisli category.

Now for the definition of $z i p\langle t\rangle$. The first case falls back on the equality of values. Thus, $e q\langle t\rangle$ and $z i p\langle f\rangle$ are mutually recursive functions, which is not surprising since $F^{(0)}$ and $F^{(1)}$ are mutually recursive as well (we tacitly identify nullary functors, $F^{(0)}$, and types, $T$ ).

$$
\begin{array}{ll}
z i p\langle f\rangle & :: \quad f a \times f b \rightarrow \text { Maybe }(f(a \times b)) \\
z i p\langle K t\rangle & =(\text { eq }\langle t\rangle \rightarrow \text { return } \circ \text { outl, const Nothing }) \\
z i p\langle I d\rangle & =\text { return } \\
z i p\langle f+g\rangle & =(z i p\langle f\rangle \oplus \text { zip }\langle g\rangle) \text { © couple } \\
z i p\langle f \times g\rangle & =(z i p\langle f\rangle \otimes z i p\langle g\rangle) \circ \text { transpose } \\
z i p\langle f \cdot g\rangle & =\text { mapM }\langle f\rangle(z i p\langle g\rangle) \text { © zip }\langle f\rangle
\end{array}
$$

The last case is again the most interesting one. To zip two values of type $f(g a)$ and $f(g b)$ we first apply $z i p\langle f\rangle$, which yields a value of type Maybe $(f(g a \times g b))$. To obtain a value of the desired type, Maybe $(f(g(a \times b))$ ), we then map zip $\langle g\rangle$ on $f$. However, since we are working within a monad we cannot use the 'ordinary' map operation as defined in Sec. 3. Instead we must employ a monadic map [7], which is defined as follows (note that map $M\langle f\rangle$ is termed mapl in [18]).

$$
\begin{array}{ll}
\operatorname{map} M\langle f\rangle & ::(\text { Monad } m) \Rightarrow(a \rightarrow m b) \rightarrow(f a \rightarrow m(f b)) \\
\operatorname{map} M\langle K t\rangle \varphi & = \\
\operatorname{return} \\
\operatorname{map} M\langle I d\rangle \varphi & =\varphi \\
\operatorname{map} M\langle f+g\rangle \varphi & =\operatorname{map} M\langle f\rangle \varphi \oplus \operatorname{map} M\langle g\rangle \varphi \\
\operatorname{map} M\langle f \times g\rangle \varphi & =\operatorname{map} M\langle f\rangle \varphi \otimes \operatorname{map} M\langle g\rangle \varphi \\
\operatorname{map} M\langle f \cdot g\rangle \varphi & =\operatorname{map} M\langle f\rangle(\operatorname{map} M\langle g\rangle \varphi)
\end{array}
$$

Abstractly speaking, $\operatorname{map} M\langle f\rangle$ defines the action on arrows in the Kleisli category induced by $m$. If we specialize $m$ to $I d$, the identity monad, we obtain the 'ordinary' map operation. Since $m a p M\langle f\rangle$ is the morphism part of a functor, it satisfies the following two functorial laws.

$$
\begin{aligned}
\operatorname{map} M\langle f\rangle \text { return } & =\text { return } \\
\operatorname{map} M\langle f\rangle(\varphi \bigcirc \psi) & =\operatorname{map} M\langle f\rangle \varphi \bigcirc \operatorname{map} M\langle f\rangle \psi \quad \text { if } m \text { is commutative }
\end{aligned}
$$

Since the proof of the last law employs equation (17), it is restricted to commutative monads, as well. The monadic map is surprisingly versatile. It may be used, for example, to thread a monad through a structure, see [11].

$$
\begin{aligned}
\text { thread }\langle f\rangle & :: \quad(\text { Monad m) } \Rightarrow f(m a) \rightarrow m(f a) \\
\text { thread }\langle f\rangle & =\text { mapM }\langle f\rangle \text { id }
\end{aligned}
$$

What about the running time of $z i p\langle f\rangle$ ? From the last equation of $z i p\langle f\rangle$ we are lead to suspect that $z i p\langle f\rangle$ suffers from the same problems as reduce $\langle f\rangle$. And this indeed is the case. Consider the specialization of $z i p\langle f\rangle$ to Tower (note that $z i p\langle$ Maybe $\rangle=$ couple).

$$
\text { zip }\langle\text { Tower }\rangle=(\text { return } \oplus \operatorname{mapM}\langle\text { Tower }\rangle \text { couple } \odot \text { zip }\langle\text { Tower }\rangle) \text { © couple }
$$

It is not hard to see that zipping ( Recurse $^{n}\left(\right.$ End $\left.\left.^{(J u s t}{ }^{n} a\right)\right)$, Recurse $^{n}\left(\right.$ End $\left.\left.\left(J u s t^{n} b\right)\right)\right)$ takes $\Theta\left(n^{2}\right)$ time. However, we can easily improve the efficiency by combining a monadic map with a zip.

$$
\begin{array}{rll}
z i p W i t h\langle f\rangle \varphi & =\operatorname{map} M\langle f\rangle \varphi \odot z i p\langle f\rangle \\
z i p\langle f\rangle & = & \text { zipWith }\langle f\rangle \text { return }
\end{array}
$$

The derivation of $z i p W i t h\langle f\rangle$ is again a simple exercise in program calculation. It pays off that we have defined $z i p\langle f\rangle$ in terms of the admittedly abstract operators on procedures.

$$
\begin{aligned}
& z i p W i t h\langle K t\rangle \varphi=\operatorname{map} M\langle K t\rangle \varphi \odot z i p\langle K t\rangle=\text { return } \bigcirc z i p\langle K t\rangle=z i p\langle K t\rangle \\
& z i p W i t h\langle I d\rangle \varphi=\operatorname{mapM}\langle I d\rangle \varphi \odot z i p\langle I d\rangle=\varphi \odot \text { return }=\varphi \\
& z i p W i t h\langle f+g\rangle \varphi=\operatorname{mapM}\langle f+g\rangle \varphi \bigcirc z i p\langle f+g\rangle \\
& =(\operatorname{map} M\langle f\rangle \varphi \oplus \operatorname{map} M\langle g\rangle \varphi) \odot(z i p\langle f\rangle \oplus z i p\langle g\rangle) \odot \text { couple } \\
& =(\operatorname{map} M\langle f\rangle \varphi \odot z i p\langle f\rangle \oplus \operatorname{map} M\langle g\rangle \varphi \odot z i p\langle g\rangle) \odot \text { couple } \\
& =(z i p W i t h\langle f\rangle \varphi \oplus \text { zipWith }\langle g\rangle \varphi) \text { © couple }
\end{aligned}
$$

The derivation for products and compositions relies on the commutativity of Maybe.

$$
\begin{aligned}
z i p \text { With }\langle f \times g\rangle \varphi & =\operatorname{map} M\langle f \times g\rangle \varphi \odot \text { zip }\langle f \times g\rangle \\
& =(\operatorname{map} M\langle f\rangle \varphi \otimes \operatorname{mapM}\langle g\rangle \varphi) \odot(z i p\langle f\rangle \otimes z i p\langle g\rangle) \circ \text { transpose } \\
& =(\operatorname{mapM}\langle f\rangle \varphi \odot z i p\langle f\rangle \otimes \operatorname{map}\langle g\rangle \varphi \odot z i p\langle g\rangle) \circ \text { transpose } \\
& =(\text { zipWith }\langle f\rangle \varphi \otimes \text { zipWith }\langle g\rangle \varphi) \circ \text { transpose } \\
\text { zipWith }\langle f \cdot g\rangle \varphi & =\operatorname{mapM}\langle f \cdot g\rangle \varphi \odot z i p\langle f \cdot g\rangle \\
& =\operatorname{map}\langle f\rangle(\operatorname{mapM}\langle g\rangle \varphi) \bigcirc \operatorname{map} M\langle f\rangle(z i p\langle g\rangle) \odot z i p\langle f\rangle \\
& =\operatorname{mapM}\langle f\rangle(\operatorname{mapM}\langle g\rangle \varphi \odot z i p\langle g\rangle) \odot z i p\langle f\rangle \\
& =\text { zipWith }\langle f\rangle(\text { zipWith }\langle g\rangle \varphi)
\end{aligned}
$$

Putting things together we obtain

$$
\begin{array}{ll}
\text { zip }\langle f\rangle & =\text { zipWith }\langle f\rangle \text { return } \\
\text { zipWith }\langle f\rangle & ::(\text { a } \times b \rightarrow \text { Maybe } c) \rightarrow(f a \times f b \rightarrow \text { Maybe }(f \text { c })) \\
\text { zipWith }\langle K t\rangle \varphi & =(\text { eq }\langle t\rangle \rightarrow \text { return } \circ \text { outl, const Nothing }) \\
\text { zipWith }\langle I d\rangle \varphi & =\varphi \\
\text { zipWith }\langle f+g\rangle \varphi & =(\text { zipWith }\langle f\rangle \varphi \oplus \text { zipWith }\langle g\rangle \varphi) \odot \text { couple } \\
\text { zipWith }\langle f \times g\rangle \varphi= & (\text { zipWith }\langle f\rangle \varphi \otimes \text { zipWith }\langle g\rangle \varphi) \circ \text { transpose } \\
\text { zipWith }\langle f \cdot g\rangle \varphi & =\text { zipWith }\langle f\rangle(\text { zipWith }\langle g\rangle \varphi) .
\end{array}
$$

Interestingly, the two definitions of $z i p\langle f\rangle$ are equivalent for arbitrary monads, not just for Maybe. To see why this is the case note that $z i p\langle f\rangle$ and $z i p W i t h\langle f\rangle$ are related by

$$
z i p\langle f \cdot g\rangle=z i p W i t h\langle f\rangle(z i p\langle g\rangle)
$$

Setting $g=I d$ yields the desired result.

### 5.2 Polybifunctorial functions

The definition of polybifunctorial functions contains little surprise. The main difference to polyfunctorial functions is that we must consider two projection functors, Fst and Snd, instead of one. Here is the definition of bimap $\langle f\rangle$, which describes the action of a bifunctor on arrows.

$$
\begin{array}{ll}
\operatorname{bimap}\langle f\rangle & ::\left(a_{1} \rightarrow b_{1}\right) \rightarrow\left(a_{2} \rightarrow b_{2}\right) \rightarrow\left(f a_{1} a_{2} \rightarrow f b_{1} b_{2}\right) \\
\operatorname{bimap}\langle K t\rangle \varphi_{1} \varphi_{2} & =\operatorname{dd} \\
\operatorname{bimap}\langle F s t\rangle \varphi_{1} \varphi_{2} & =\varphi_{1} \\
\operatorname{bimap}\langle\operatorname{Snd}\rangle \varphi_{1} \varphi_{2} & =\varphi_{2} \\
\operatorname{bimap}\langle f+g\rangle \varphi_{1} \varphi_{2} & =\operatorname{bimap}\langle f\rangle \varphi_{1} \varphi_{2}+\operatorname{bimap}\langle g\rangle \varphi_{1} \varphi_{2} \\
\operatorname{bimap}\langle f \times g\rangle \varphi_{1} \varphi_{2} & =\operatorname{bimap}\langle f\rangle \varphi_{1} \varphi_{2} \times \operatorname{bimap}\langle g\rangle \varphi_{1} \varphi_{2} \\
\operatorname{bimap}\langle f \cdot g\rangle \varphi_{1} \varphi_{2} & =\operatorname{map}\langle f\rangle\left(\operatorname{bimap}\langle g\rangle \varphi_{1} \varphi_{2}\right) \\
\operatorname{bimap}\left\langle f \cdot\left(g_{1}, g_{2}\right)\right\rangle \varphi_{1} \varphi_{2} & =\operatorname{bimap}\langle f\rangle\left(\operatorname{bimap}\left\langle g_{1}\right\rangle \varphi_{1} \varphi_{2}\right)\left(\operatorname{bimap}\left\langle g_{2}\right\rangle \varphi_{1} \varphi_{2}\right)
\end{array}
$$

Note the interplay of $\operatorname{map}\langle f\rangle$ and $\operatorname{bimap}\langle f\rangle$. For reasons of symmetry the following equation should be added to the definition of $\operatorname{map}\langle f\rangle$.

$$
\operatorname{map}\left\langle f \cdot\left(g_{1}, g_{2}\right)\right\rangle \varphi=\operatorname{bimap}\langle f\rangle\left(\operatorname{map}\left\langle g_{1}\right\rangle \varphi\right)\left(\operatorname{map}\left\langle g_{2}\right\rangle \varphi\right)
$$

The example of $\operatorname{map}\langle f\rangle$ illustrates a problem inherent with all polytypic definitions. If an unary functor, say, $f$ is defined in terms of a ternary functor, then $\operatorname{map}\langle f\rangle$ is undefined. The reason is simply that the relevant case $f \cdot\left(g_{1}, g_{2}, g_{3}\right)$ is missing in map $\langle f\rangle$ 's definition. Moreover, since $f \cdot\left(g_{1}, \ldots, g_{k}\right)$ is an element of $F^{(n)}$ for all $k \geqslant 1$, we cannot define $\operatorname{map}\langle f\rangle$ exhaustively. Clearly, further research is required here.

The generalization of polytypic reductions to binary functors is left as an exercise to the reader. Note that, in general, a reduction is a function of type $f a \ldots a \rightarrow a$.

## 6 Related and future work

The impetus for writing this article came while reading the article "Nested Datatypes" by R. Bird and L. Meertens [3]. The authors state that "It is possible to define reductions completely generically for all regular types [...], but we do not know at present whether the same can be done for nested datatypes." We have shown that the answer to this question is in the affirmative. Moreover, the solution presented is surprisingly simple. To define a polytypic function it suffices to specify its action on polynomial functors. The extension to (mutually) recursive datatypes-which is uniquely defined-is then handled automatically by the system. This does not only simplify matters for the generic programmer, it also removes some of the redundancy present in the classical approach. In the polytypic programming language PolyP [10], for instance, the user must supply definitions for both polynomial and type functors. There is, however, no guarantee that the corresponding functions behave in related ways.

Very recently, R. Bird and R. Paterson [4] introduced so-called generalised folds, which overcome some of the problems mentioned in the introduction to this article. Generalised folds, which can be constructed systematically for each first-order polymorphic datatype, possess a uniqueness property analogous to that of ordinary folds. Their work is largely complementary to ours. While generalised folds are more general than the reductions defined in Sec. 4, it is not clear how to define functions like sum generically using generalised folds.

An obvious disadvantage of our approach is that it is not possible to define general recursion schemes like cata- and anamorphisms (ie folds and unfolds) [16]. The reason is simply that type recursion is left implicit rather than made explicit. The situation can be saved, however, by introducing an operation on functors that maps a type functor to its base functor. Inventing a notation we define $F^{\prime}=B$ for $F=\mu B$ (the operation $(-)^{\prime}$ corresponds to the type constructor FunctorOf used in PolyP). Of course, $F^{\prime}$ is only defined if $F$ is a regular functor. Given two functions in :: $t^{\prime} t \rightarrow t$ and out $:: t \rightarrow t^{\prime} t$ we can now define

$$
\begin{array}{ll}
\text { cata }\langle t\rangle & :: \quad\left(t^{\prime} a \rightarrow a\right) \rightarrow(t \rightarrow a) \\
\text { cata }\langle t\rangle \varphi & =\text { 甲 } \circ \operatorname{map}\left\langle t^{\prime}\right\rangle(\operatorname{cata}\langle t\rangle \varphi) \circ \text { out } \\
\text { ana }\langle t\rangle & ::\left(a \rightarrow t^{\prime} a\right) \rightarrow(a \rightarrow t) \\
\text { ana }\langle t\rangle \psi & =\text { in } \circ \operatorname{map}\left\langle t^{\prime}\right\rangle(\operatorname{ana}\langle t\rangle \psi) \circ \psi .
\end{array}
$$

Ironically, hylomorphisms can be defined without any additions since their type does not involve type functors.

$$
\begin{array}{ll}
\text { hylo }\langle f\rangle & :: \quad(f a \rightarrow a) \rightarrow(b \rightarrow f b) \rightarrow(b \rightarrow a) \\
\text { hylo }\langle f\rangle \varphi \psi & =\varphi \circ \operatorname{map}\langle f\rangle(\text { hylo }\langle f\rangle \varphi \psi) \circ \psi
\end{array}
$$

Polytypic functions are values that depend on types. For that reason they cannot be expressed in languages such as Haskell or Standard ML. The question naturally arises as to whether polytypic definitions can be easily added to languages that incorporate dependent types such as Cayenne [2]. Now, since polytypic functions perform pattern matching on types, this would entail the addition of a typecase [1]. A typecase was, however, left out of Cayenne by design and the consequences of adding such a construct to the language are unclear (personal communication with L. Augustsson). The transformational approach taken here-to specialize a polytypic function for each given instance-appears to be simpler and also more efficient since the repeated matching of the type argument (which is statically known at compile time) is avoided.

Directions for future work suggest themselves. It remains to broaden the approach to include exponentials and higher-order polymorphism [13]. The former extension should be fairly straightforward, see [22] or [17]. The latter extension is far more challenging. To illustrate, consider the following generalization of rose trees.

$$
\text { data GRosef } a=\text { Node } a(f(\text { GRose } f a))
$$

This datatype is used, for instance, to extend an implementation of collections (sequences or priority queues) with an efficient operation for combining two collections (catenate or meld), see [20]. From a categorical point of view we could interpret GRose as a higher-order functor of type $\operatorname{Fun}(\mathbf{C}) \rightarrow F u n(\mathbf{C})$, where $\operatorname{Fun}(\mathbf{C})$ is the category that has as objects functors of type $\mathbf{C} \rightarrow \mathbf{C}$ and as arrows natural transformations between them. Equating natural transformations and polymorphic functions it follows that GRose's map functional has the type $(\forall a . f a \rightarrow g a) \rightarrow(\forall a . G R o s e f a \rightarrow$ GRose $g a)$. Unfortunately, this is a rank-2 type, which is not legal Haskell. An alternative view is to interpret GRose as a higher-order functor of type $\operatorname{Cat}(\mathbf{C}) \rightarrow \operatorname{Cat}(\mathbf{C})$, where $\operatorname{Cat}(\mathbf{C})$ is the category that has as the only object the category $\mathbf{C}$ and as arrows functors of type $\mathbf{C} \rightarrow \mathbf{C}$. This suggests to define a higher-order map of type $(\forall a . \forall b .(a \rightarrow b) \rightarrow(f a \rightarrow f b)) \rightarrow(\forall a . \forall b .(a \rightarrow b) \rightarrow($ GRose $a \rightarrow$ GRose $f b)$ ). Both maps are clearly useful: The first operates on the base collection $f$ of the 'bootstrapped' collection GRose $f$ while the second operates on the elements contained in a collection. However, it is far from clear how to define these maps generically for all higher-order datatypes.

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[^0]:    ${ }^{\dagger}$ An extended abstract of this article appeared in the proceedings of the 3rd Latin-American Conference on Functional Programming (CLaPF'99).

[^1]:    ${ }^{\ddagger}$ By 'equal' we mean semantic equality of functors, see below.

[^2]:    ${ }^{\S}$ Examples are given in a pidgin based on the functional programming language Haskell 98 [21]. We assume, however, that primitive functions are non-curried, ie $(\wedge)$ has type Bool $\times$ Bool $\rightarrow$ Bool rather than Bool $\rightarrow($ Bool $\rightarrow$ Bool $)$.

[^3]:    II We tacitly assume that computations do not diverge. Otherwise this property does not hold, take, for instance, $h_{1} a_{1}=$ Nothing and $h_{2} a_{2}=\perp$.

